

An Efficient Non-Linear Estimator for Estimating the Finite Population Distribution Function under Simple Random Sampling Design

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Article Info:

Submitted:	Revised:	Accepted:	Published:
Jul 25, 2024	Aug 18, 2024	Aug 30, 2024	Sep 3, 2024

Abstract

The main purpose of this paper is to propose an efficient non-linear estimator for estimating the population distribution function under Simple Random Sampling (SRS). The properties (Bias and Mean Square Error (MSE)) of the suggested estimator are obtained up to the first-order approximation using Taylor's series expansion approach. The performance of the proposed estimator over some existing estimators is theoretically compared and efficiency conditions under which the proposed estimator outperforms existing estimators were obtained. The theoretical findings are supported numerically by empirical studies using five different population data sets and the result shows that the proposed estimator performed better than the existing estimators considered in the literature.

Keywords: Auxiliary variable, Exponential estimator, Cumulative Distribution Function

Symbols and Notations

$I(\cdot)$: Indicator variable

Y : The study variable

X : The auxiliary variable

$I(Y \leq t_y)$: Indicator variable based on Y

$I(X \leq t_x)$: Indicator variable based on X

$$\hat{F}_Y(t_y) = \frac{\sum_{i=1}^n I(Y_i = t_y)}{n} : \text{The sample distribution function of } Y$$

$$\hat{F}_X(t_x) = \frac{\sum_{i=1}^n I(X_i = t_x)}{n} : \text{The sample distribution function of } X$$

$$S_{F_Y(t_y)}^2 = \frac{\sum_{i=1}^N [I(Y_i \leq t_y) - F_Y(t_y)]^2}{(N-1)} : \text{The population variance of } I(Y \leq t_y)$$

$$S_{F_X(t_x)}^2 = \frac{\sum_{i=1}^N [I(X_i \leq t_x) - F_X(t_x)]^2}{(N-1)} : \text{The population variance of } I(X \leq t_x)$$

$$C_{F_Y(t_y)} = \frac{S_{F_Y(t_y)}}{F_Y(t_y)} : \text{The population coefficient of variation of } I(Y \leq t_y)$$

$$C_{F_X(t_x)} = \frac{S_{F_X(t_x)}}{F_X(t_x)} : \text{The population coefficient of variation of } I(X \leq t_x)$$

$$S_{F_Y(t_y)F_X(t_x)} = \frac{\sum_{i=1}^N [I(Y_i \leq t_y) - F_Y(t_y)][I(X_i \leq t_x) - F_X(t_x)]}{(N-1)} : \text{The population covariance}$$

between $I(Y \leq t_y)$ and $I(X \leq t_x)$

$$R_{F_Y(t_y)F_X(t_x)} = \frac{S_{F_Y(t_y)F_X(t_x)}}{S_{F_Y(t_y)}S_{F_X(t_x)}} : \text{The population correlation coefficient between } I(Y \leq t_y) \text{ and}$$

$I(X \leq t_x)$.

Introduction

Many scholars have examined the use of an auxiliary variable in the literature of survey sampling to improve the effectiveness of their developed estimators for estimating common parameters such as mean, total, variance, and among others, in such cases, traditional ratio, product and regression estimators produce reliable outcomes for parameters that are not known.

The ratio approach and the product method have been frequently utilized for estimating unknown population parameters where there is a high positive and negative correlation between the study parameter and supplementary variable. Several authors have already presented many ratio type and product type estimators applying various types of linear transformation of the original auxiliary variables. The drawback of these classic of estimators is that they require a very precise linear transformation of the auxiliary variable, which limits the scope of applications of this classic in practice. To address this limitation, we offer a non-linear transformation class estimator of the population distribution function in this paper.

The problem of estimating the finite population distribution function occurs when it is desired to know the proportion of study variable values that are less or equal to a given value. Estimating CDF is required in a variety of scenarios for economists, for instance, it is interesting to know the proportion of the population that 25% or more Nigerians do not have skills. Similarly, a soil scientist may be interested in determining the percentage of clay in the soil. Furthermore, policymakers may be interested in understanding the proportion of people living in a developing country below the poverty line.

An extensive literature is available on the estimation of population mean, total, etc. However, no effort has been devoted to the development of efficient methods for population cumulative distribution function; here our focus is on the estimation of the finite population CDF with supplementary variables. Chambers and Dunstan (1986) consider the estimation of the population CDF and quantiles with a model-based approach, on a similar line to Rao et al (1990) proposed ratio and regression estimators for estimating the CDF under a general sampling scheme, Singh et al (2008) consider the problem of estimating the CDF and quantiles with the use of auxiliary variable at the estimation stage of the survey. To the base of our knowledge, recent research may be seen in Martinez et al (2010), Mayer et al (2010), Berger and Munoz (2015), Hussain et al (2020),

Yakubu and Shabbir (2020), GaribNath Singh and Mahmood Usman (2021), Sardar et al (2022), Rueda and Illescas (2022), Ahmad et al (2022), Mohsin Abbas and Abdul Haqto (2022), Sohaib Ahmad et al (2023) name a few.

Materials and Methods

Consider a finite identifiable population $U = \{U_1, U_2, \dots, U_N\}$ having N distinct units. Let y_i and x_i be the i^{th} values of the study variable Y and auxiliary variable X which takes the values such that $(y_i, x_i) \in U_i$ in U . We assumed that the information for all the units of X is available in the population. The problem is to estimate the CDF of $F_Y(t_y)$ and $F_X(t_x)$ Y and X respectively which defined as

$$F_Y(t_y) = \frac{1}{N} \sum_{i \in u} I(Y \leq t_y) \text{ and } F_X(t_x) = \frac{1}{N} \sum_{i \in u} I(X = t_x)$$

The usual unbiased estimator $F_{Y_{us}}(t_y)$ as well as its variance are given in (1) and (2) respectively

$$\hat{F}_{Y_{usual}}(t_y) = \frac{\sum_{i=1}^n I(Y_i = t_y)}{n} \quad (1)$$

$$\text{Var}(\hat{F}_{Y_{usual}}(t_y)) = F_Y^2(t_y) \xi_{20} \quad (2)$$

Following Cochran (1940), ratio type estimator of $F_Y(t_y)$ denoted by $\hat{F}_{Y_c}(t_y)$ as well as its bias and MSE are given in (3), (4), and (5), respectively

$$\hat{F}_{Y_c}(t_y) = \hat{F}_Y(t_y) \left[\frac{F_X(t_x)}{\hat{F}_X(t_x)} \right] \quad (3)$$

$$\text{Bias}[\hat{F}_{Y_c}(t_y)] = \hat{F}_Y(t_y) (\xi_{02} - \xi_{11}) \quad (4)$$

$$\text{MSE}[\hat{F}_{Y_c}(t_y)] = F_Y^2(t_y) (\xi_{20} + \xi_{02} - 2\xi_{11}) \quad (5)$$

Following Murthy (1964), the product estimator of $F_Y(t_y)$ denoted by $\hat{F}_{Y_m}(t_y)$ as well as its bias and MSE are given in (6), (7), and (8), respectively

$$\hat{F}_{Y_m}(t_y) = \hat{F}_Y(t_y) \left[\frac{\hat{F}_X(t_x)}{F_X(t_x)} \right] \tag{6}$$

The bias and MSE of Equation (6) are

$$Bias[\hat{F}_{Y_m}(t_y)] = F_Y(t_y) \xi_{11} \tag{7}$$

$$MSE[\hat{F}_{Y_m}(t_y)] = F_Y^2(t_y) (\xi_{20} + \xi_{02} + 2\xi_{11}) \tag{8}$$

Following Bahl and Tuteja (1991), ratio type and product type exponential estimator of $F_Y(t_y)$ denoted by $\hat{F}_{Y_{BTR}}(t_y)$ as well as its bias and MSE are given in (9), (10), (11), (12), (13), and (14), respectively

$$\hat{F}_{Y_{BTR}}(t_y) = \hat{F}_Y(t_y) \exp \left[\frac{F_X(t_x) - \hat{F}_X(t_x)}{F_X(t_x) + \hat{F}_X(t_x)} \right] \tag{9}$$

$$\hat{F}_{Y_{BTP}}(t_y) = \hat{F}_Y(t_y) \exp \left[\frac{\hat{F}_X(t_x) - F_X(t_x)}{\hat{F}_X(t_x) + F_X(t_x)} \right] \tag{10}$$

The bias and MSE of equation (9) and (10) are given below

$$Bias[\hat{F}_{Y_{BTR}}(t_y)] = \frac{F_Y(t_y)}{4} \left(\frac{3}{2} \xi_{02} - 2\xi_{11} \right) \tag{11}$$

$$MSE[\hat{F}_{Y_{BTR}}(t_y)] = \frac{F_Y^2(t_y)}{4} (4\xi_{20} + \xi_{02} - 4\xi_{11}) \tag{12}$$

$$Bias[\hat{F}_{Y_{BTP}}(t_y)] = \frac{F_Y(t_y)}{4} \left(2\xi_{11} - \frac{1}{2} \xi_{02} \right) \tag{13}$$

$$MSE[\hat{F}_{Y_{BTP}}(t_y)] = \frac{F_Y^2(t_y)}{4} (4\xi_{20} + \xi_{02} + 4\xi_{11}) \tag{14}$$

Following Sisodia and Dwivedi (1981) proposed ratio type estimator of $F_Y(t_y)$ denoted by $\hat{F}_{Y_{sd}}(t_y)$ as well as its bias and MSE are given in (15), (16), and (17), respectively

$$\hat{F}_{Y_{sd}}(t_y) = \hat{F}_Y(t_y) \left[\frac{F_X(t_x) + C_{F_X(t_x)}}{\hat{F}_X(t_x) + C_{F_X(t_x)}} \right] \tag{15}$$

The bias and MSE of equation (15) are given as

$$Bias[\hat{F}_{Y_{sd}}(t_y)] = F_Y(t_x) (\lambda^2 \xi_{02} - 2\lambda \xi_{11}) \tag{16}$$

$$MSE\left[\hat{F}_{Y_{sd}}(t_y)\right] = F_Y^2(t_y)\left(\xi_{20} + \lambda^2\xi_{02} - 2\lambda\xi_{11}\right) \quad (17)$$

$$\text{where, } \lambda = \frac{F_X(t_x)}{F_X(t_x) + C_{F_X(t_x)}}$$

Following Upadhyaya and Singh (1999) proposed ratio type estimator of $F_Y(t_y)$ denoted by $\hat{F}_{Y_{ups}}(t_y)$ as well as its bias and MSE are given in (18), (19), and (20), respectively

$$\hat{F}_{Y_{ups}}(t_y) = \hat{F}_Y(t_y) \left[\frac{F_X(t_x)C_{F_X(t_x)} + \beta_2}{\hat{F}_X(t_x)C_{F_X(t_x)} + \beta_2} \right] \quad (18)$$

The bias and MSE of equation (18) are given below

$$Bias\left[\hat{F}_{Y_{ups}}(t_y)\right] = F_Y(t_x)\left(\delta^2\xi_{02} - 2\delta\xi_{11}\right) \quad (19)$$

$$MSE\left[\hat{F}_{Y_{ups}}(t_y)\right] = F_Y^2(t_y)\left(\xi_{20} + \delta^2\xi_{02} - 2\delta\xi_{11}\right) \quad (20)$$

$$\text{Where } \delta = \frac{F_X(t_x)C_{F_X(t_x)}}{F_X(t_x)C_{F_X(t_x)} + \beta_2}$$

Following Singh and Tailor (2003) ratio estimator of $F_{Y_{us}}(t_y)$ denoted by $\hat{F}_{st}(t_y)$ as well as its bias and MSE are given in (21), (22), and (23), respectively

$$\hat{F}_{Y_{st}}(t_y) = \hat{F}_Y(t_y) \left[\frac{F_X(t_x) + R_{F_Y(t_y)F_X(t_x)}}{\hat{F}_X(t_x) + R_{F_Y(t_y)F_X(t_x)}} \right] \quad (21)$$

The bias and MSE of equation (21) is obtained as

$$Bias\left[\hat{F}_{Y_{st}}(t_y)\right] = F_Y(t_x)\left(\gamma^2\xi_{02} - 2\gamma\xi_{11}\right) \quad (22)$$

$$MSE\left[\hat{F}_{Y_{st}}(t_y)\right] = F_Y^2(t_y)\left(\xi_{20} + \gamma^2\xi_{02} - 2\gamma\xi_{11}\right) \quad (23)$$

where; $\gamma = \frac{F_X(t_x)}{F_X(t_x) + R_{F_Y(t_y)F_X(t_x)}}$

Following Singh *et al.* (2004) estimator of $F_{Y_{us}}(t_y)$ denoted by $\hat{F}_{Y_{se}}(t_y)$ as well as its bias and MSE are given in (24), (25) and (26), respectively

$$\hat{F}_{Y_{se}}(t_y) = \hat{F}_Y(t_y) \left[\frac{F_X(t_x) + \beta_2}{\hat{F}_X(t_x) + \beta_2} \right] \tag{24}$$

The bias and MSE of equation (24) are

$$Bias[\hat{F}_{Y_{se}}(t_y)] = F_Y(t_x)(\phi^2 \xi_{02} - 2\phi \xi_{11}) \tag{25}$$

$$MSE[\hat{F}_{Y_{se}}(t_y)] = F_Y^2(t_y)(\xi_{20} + \phi^2 \xi_{02} - 2\phi \xi_{11}) \tag{26}$$

where; $\phi = \frac{F_X(t_x)}{F_X(t_x) + \beta_2}$

Following Jerajuddin and Kishun (2016) estimator of population mean $F_{Y_{us}}(t_y)$ denoted by $\hat{F}_{Y_{jk}}(t_y)$ as well as its bias and MSE are given in (27), (28) and (29), respectively

$$\hat{F}_{Y_{jk}}(t_y) = \hat{F}_Y(t_y) \left[\frac{F_X(t_x) + n}{\hat{F}_X(t_x) + n} \right] \tag{27}$$

The bias and MSE of equation (27) are obtained as follows

$$Bias[\hat{F}_{Y_{jk}}(t_y)] = F_Y(t_x)(\tau^2 \xi_{02} - 2\tau \xi_{11}) \tag{28}$$

$$MSE[\hat{F}_{Y_{jk}}(t_y)] = F_Y^2(t_y)(\xi_{20} + \tau^2 \xi_{02} - 2\tau \xi_{11}) \tag{29}$$

Where $\tau = \frac{F_X(t_x) + n}{F_X(t_x) + n}$

Following Gupta and Yadav (2018) suggested the improved estimation based on Jerajuddin and Kishun (2016) estimator in population mean $F_{Y_{us}}(t_y)$ denoted by $\hat{F}_{Y_{jk}}(t_y)$ as well as its bias and MSE is given in (30), (31) and (32), respectively

$$\hat{F}_{Y_{gy}}(t_y) = \hat{F}_Y(t_y) \left[\alpha + (1-\alpha) \left(\frac{F_X(t_x) + n}{\hat{F}_X(t_x) + n} \right) \right] \tag{30}$$

The bias and MSE obtained as

$$Bias[\hat{F}_{Y_{gy}}(t_y)] = F_Y(t_x) (\alpha^2 \xi_{02} - \eta \xi_{11} + \alpha \eta \xi_{11} - \alpha \eta^2 \xi_{02}) \tag{31}$$

$$MSE[\hat{F}_{Y_{gy}}(t_y)] = F_Y^2(t_y) \left\{ \xi_{20} + \eta^2 \xi_{02} - 2\eta \xi_{11} - \left[\frac{(\eta^2 \xi_{02} - \eta \xi_{11})^2}{\eta^2 \xi_{02}} \right] \right\} \tag{32}$$

Where; $\eta = \frac{F_X(t_x) + n}{F_X(t_x) + n}$

Propose estimator

motivated by Ahmad et al (2021), we proposed an efficient non-linear estimator of finite population cumulative distribution function as

$$\hat{F}_{Y_{AD}}(t_y) = \hat{F}_Y(t_y) \left\{ \frac{1}{2} \left[\gamma^{\left(\frac{F_X(t_x) - \hat{F}_X(t_x)}{F_X(t_x) + \hat{F}_X(t_x)} \right)} + \exp \left(\frac{\hat{F}_X(t_x) - F_X(t_x)}{\hat{F}_X(t_x) + F_X(t_x)} \right) \right] \right\} \tag{33}$$

Where γ is constant

To obtain the bias and MSE, we define

$$E(e_0) = \frac{\hat{F}_Y(t_y) - F_Y(t_y)}{F_Y(t_y)} \text{ And } E(e_1) = \frac{\hat{F}_X(t_x) - F_X(t_x)}{F_X(t_x)} \text{ Such that } E(e_0) = E(e_1) = 0$$

$$\left. \begin{aligned} E(e_0^2) &= \left(\frac{1}{n} - \frac{1}{N} \right) C_{F_Y(t_y)}^2 = \xi_{20} \\ E(e_1^2) &= \left(\frac{1}{n} - \frac{1}{N} \right) C_{F_X(t_x)}^2 = \xi_{02} \\ E(e_0 e_1) &= \left(\frac{1}{n} - \frac{1}{N} \right) R_{F_Y(t_y) F_X(t_x) C_{F_Y(t_y)} C_{F_X(t_x)}} = \xi_{11} \end{aligned} \right\} \tag{34}$$

Taylor’s Expansion was used for the derivation of properties (Bias, Mean Square Error, and Minimum Mean Square Error) of the proposed estimator.

Now expressing (33) in error terms as:

$$\hat{F}_{Y_{AD}}(t_y) = F_Y(t_y)(1 + e_0) \left\{ \frac{1}{2} \left[\gamma^{\left(\frac{F_X(t_x) - F_X(t_x)(1+e_1)}{F_X(t_x) + F_X(t_x)(1+e_1)} \right)} + \exp\left(\frac{F_X(t_x)(1+e_1) - F_X(t_x)}{F_X(t_x)(1+e_1) + F_X(t_x)} \right) \right] \right\}$$

$$\hat{F}_{Y_{AD}}(t_y) = F_Y(t_y)(1 + e_0) \left\{ \frac{1}{2} \left[\gamma^{\left(\frac{-e_1}{2+e_1} \right)} + \exp\left(\frac{e_1}{2+e_1} \right) \right] \right\}$$

$$\hat{F}_{Y_{AD}}(t_y) = F_Y(t_y)(1 + e_0) \left\{ \frac{1}{2} \left[\gamma^{\left(\frac{-e_1}{2+e_1} \right)} + \exp\left(\frac{e_1}{2+e_1} \right) \right] \right\}$$

$$\hat{F}_{Y_{AD}}(t_y) = F_Y(t_y)(1 + e_0) \left\{ \frac{1}{2} \left[\gamma^{\left(\frac{-e_1}{2} \right) \left(1 - \frac{e_1}{2} + \frac{e_1^2}{4} \right)} + \exp\left(\frac{e_1}{2} \right) \left(1 - \frac{e_1}{2} + \frac{e_1^2}{4} \right) \right] \right\}$$

$$\hat{F}_{Y_{AD}}(t_y) = F_Y(t_y)(1 + e_0) \left\{ \frac{1}{2} \left[\exp\left(\ln \gamma^{\left(\frac{e_1}{2} + \frac{e_1^2}{4} \right)} \right) + \exp\left(\frac{e_1}{2} + \frac{e_1^2}{4} \right) \right] \right\}$$

Neglecting the term of order more than two because we restricted to first order approximation, we have,

$$\hat{F}_{Y_{AD}}(t_y) = F_Y(t_y)(1 + e_0) \left\{ \frac{1}{2} \left[2 - \frac{(\ln \gamma)e_1}{2} + \frac{(\ln \gamma)e_1^2}{4} + \frac{(\ln \gamma)^2 e_1^2}{8} + \frac{e_1}{2} - \frac{e_1^2}{8} \right] \right\}$$

$$\hat{F}_{Y_{AD}}(t_y) = F_Y(t_y)(1 + e_0) \left[1 - \frac{(\ln \gamma)e_1}{4} + \frac{(\ln \gamma)e_1^2}{8} + \frac{(\ln \gamma)^2 e_1^2}{16} + \frac{e_1}{4} - \frac{e_1^2}{16} \right]$$

$$\hat{F}_{Y_{AD}}(t_y) = F_Y(t_y) \left[\begin{aligned} & 1 - \frac{(\ln \gamma)e_1}{4} + \frac{(\ln \gamma)e_1^2}{8} + \frac{(\ln \gamma)^2 e_1^2}{16} + \frac{e_1}{4} - \frac{e_1^2}{16} + e_0 - \frac{e_0 e_1 (\ln \gamma)}{4} + \\ & \left[\frac{e_0 e_1}{4} \right] \end{aligned} \right] \quad (35)$$

Subtracting $F_Y(t_y)$ from both sides of (35) we have,

$$\hat{F}_{Y_{AD}}(t_y) - F_Y(t_y) = F_Y(t_y) \left[\begin{aligned} & e_0 + \frac{e_1}{4} + \frac{e_0 e_1}{4} - \frac{(\ln \gamma)e_1}{4} + \frac{(\ln \gamma)e_1^2}{8} + \frac{(\ln \gamma)^2 e_1^2}{16} - \frac{e_1^2}{16} - \\ & \left[\frac{(\ln \gamma)e_0 e_1}{4} \right] \end{aligned} \right] \quad (36)$$

Taking Expectations of both sides of (36)

$$E\left[\hat{F}_{Y_{AD}}(t_y) - F_Y(t_y)\right] = F_Y(t_y) E\left[e_0 + \frac{e_1}{4} + \frac{e_0 e_1}{4} - \frac{e_1^2}{16} - \frac{(\ln \gamma) e_1}{4} + \frac{(\ln \gamma) e_1^2}{8} + \frac{(\ln \gamma)^2 e_1^2}{16} - \frac{(\ln \gamma) e_0 e_1}{4}\right]$$

Applying the results of (34) obtaining the *Bias* $\left[\hat{F}_{Y_{AD}}(t_y)\right]$ as

$$Bias\left[\hat{F}_{Y_{AD}}(t_y)\right] = \frac{F_Y(t_x)}{4} \left\{ (1 - \ln \gamma) \xi_{11} - \frac{\xi_{02}}{4} \left[1 - 2 \ln \gamma - (\ln \gamma)^2 \right] \right\} \quad (37)$$

To obtain the MSE, we square both sides of (36) as well as expectations to both sides we have,

$$E\left[\hat{F}_{Y_{AD}}(t_y) - F_Y(t_y)\right]^2 = F_Y^2(t_y) E\left[e_0 + \frac{e_1}{4} - \frac{(\ln \gamma) e_1}{4}\right]^2$$

By simplifying the above expression, we obtain the MSE of the proposed estimator $\hat{F}_{Y_{AD}}(t_y)$ as

$$MSE\left[\hat{F}_{Y_{AD}}(t_y)\right] = \frac{F_Y^2(t_y)}{4} \left\{ 4\xi_{20} + \frac{\xi_{02}}{4} \left[1 + (\ln \gamma)^2 - 2 \ln \gamma \right] + 2\xi_{11} (1 - \ln \gamma) \right\} \quad (38)$$

To obtain the minimum MSE of the proposed estimator, we differentiate (38) with respect to γ and equate the derivative to zero as;

$$\frac{\partial MSE\left[\hat{F}_{Y_{AD}}(t_y)\right]}{\partial \gamma} = \frac{F_Y^2(t_y)}{4} \left[\ln \gamma \xi_{02} - \xi_{02} - 4\xi_{11} \right] = 0$$

$$\gamma_{opt} = e^\psi \quad \text{Where } \psi = 1 + \frac{4\xi_{11}}{\xi_{02}}$$

When we substitute γ_{opt} in (38) we have a minimum MSE of $\hat{F}_{Y_{AD}}(t_y)$ as

$$MSE_{\min}\left[\hat{F}_{Y_{AD}}(t_y)\right] = \frac{F_Y^2(t_y)}{4} \left\{ 4\xi_{20} + \frac{\xi_{02}}{4} \left[1 + \psi^2 - 2\psi \right] + 2\xi_{11} (1 - \psi) \right\}$$

Efficiency condition

In this section efficiency of the proposed estimator is compared with the efficiencies of some existing estimators in the literature. The proposed estimator $\hat{F}_{Y_{AD}}(t_y)$ is more efficient than

1. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < \hat{F}_{Y_{usual}}(t_y)$$

$$\frac{\xi_{02}}{16}(1+\psi^2-2\psi) - \frac{1}{2}\xi_{11}(1-\psi) < 0$$

2. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE[\hat{F}_{Y_c}(t_y)]$$

$$\frac{(\psi-2)}{\xi_{02}}(\psi\xi_{02} - 8\xi_{11}) < 15$$

3. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE[\hat{F}_{Y_m}(t_y)]$$

$$\psi \left(\psi - \frac{8\xi_{11}}{\xi_{02}} - 2 \right) < 15$$

4. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE[\hat{F}_{Y_{BTR}}(t_y)]$$

$$\psi(\psi-2) - \frac{8\xi_{11}}{\xi_{02}}(\psi-3) < 3$$

5. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE[\hat{F}_{Y_{BTP}}(t_y)]$$

$$\psi(\psi-2) - \frac{8\xi_{11}}{\xi_{02}}(1+\psi) < 3$$

6. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE[\hat{F}_{Y_{St}}(t_y)]$$

$$\xi_{02} (1 + \psi^2 - 2\psi) + 8\xi_{11} (1 - \psi) < 16\lambda (\lambda \xi_{02} - \xi_{11})$$

7. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE [\hat{F}_{UPS}(t_y)]$$

$$\xi_{02} (1 + \psi^2 - 2\psi) + 8\xi_{11} (1 - \psi) < 16\delta (\delta \xi_{02} - 2\xi_{11})$$

8. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE [\hat{F}_{TS}(t_y)]$$

$$\xi_{02} (1 + \psi^2 - 2\psi) + 8\xi_{11} (1 - \psi) < 16\gamma (\gamma \xi_{02} - 2\xi_{11})$$

9. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE [\hat{F}_{SE}(t_y)]$$

$$\xi_{02} (1 + \psi^2 - 2\psi) + 8\xi_{11} (1 - \psi) < 16\phi (\phi \xi_{02} - 2\xi_{11})$$

10. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE [\hat{F}_{JK}(t_y)]$$

$$\xi_{02} (1 + \psi^2 - 2\psi) + 8\xi_{11} (1 - \psi) < 16\tau (\tau \xi_{02} - 2\xi_{11})$$

11. If;

$$MSE_{\min} [\hat{F}_{Y_{AD}}(t_y)] < MSE [\hat{F}_{GY}(t_y)]$$

$$\xi_{02} (1 + \psi^2 - 2\psi) + 8\xi_{11} (1 - \psi) < 16\eta (\eta \xi_{02} - 2\xi_{11})$$

Where $\lambda = \frac{F_X(t_x)}{F_X(t_x) + C_{F_X(t_x)}}$, $\delta = \frac{F_X(t_x)C_{F_X(t_x)}}{F_X(t_x)C_{F_X(t_x)} + \beta_2}$, $\gamma = \frac{F_X(t_x)}{F_X(t_x) + R_{F_Y(t_y)F_X(t_x)}}$,

$$\phi = \frac{F_X(t_x)}{F_X(t_x) + \beta_2}$$

$$\tau = \frac{F_X(t_x) + n}{F_X(t_x) + n}, \eta = \frac{F_X(t_x) + n}{F_X(t_x) + n}$$

Empirical study

In this section, an empirical evaluation is presented to evaluate the performance of the suggested estimator and some of the existing estimators by using five different populations.

Population I

[Source:Singh 2003]

Y: Duration of sleep (in minutes) and

X: Age of old persons.

Population II

[Source: Gujarati2009]

Y: The eggs produced in 1990 (millions) and

X: The price per dozen (cents) in 1990

Population III

[Source: Murthy, 1967]

Y: The output of the factory and

X: The number of workers

Population IV

[Source: Sarndal, 1992a]

Y: Population in 1983 (in million) and

X: Population in 1980 (in million)

Population V

[Source:Koyuncuand Kadilar, 2009]

Y: Number of teachers and

X: Number of students

Table 1: Summary statistics for Population I-V

Parameters	Population I	Population II	Population III	Population IV	Population V
N	30	50	80	120	923
n	5	5	10	20	180
λ	0.16667	0.18	0.0875	0.04167	0.00447
$Q_{2(y)}$	387	831	5105	9.25	171
$Q_{2(x)}$	66.5	75.35	148	8.6	4123
$F_Y(t_y)$	0.5	0.5	0.5	0.5	0.50163
$C_{F_Y(t_y)}$	1.01709	1.01015	1.00631	1.00419	0.99729
$F_X(t_x)$	0.5	0.5	0.5	0.5	0.50054
$C_{F_X(t_x)}$	1.01709	1.01015	1.00631	1.00419	0.99946
$R_{F_Y(t_y)F_X(t_x)}$	-0.73333	-0.12000	0.95	0.96667	0.84616
β_1	1	1	1	1	1

Table 2: MSE for Population I-V

Estimator	Population I	Population II	Population III	Population IV	Population V
$\hat{F}_{Y_{usual}}(t_y)$	0.0431039	0.0459181	0.0221519	0.0105050	0.0011187
$\hat{F}_{Y_c}(t_y)$	0.1494264	0.1028566	0.0022152	0.0007003	0.0003450
$\hat{F}_{Y_m}(t_y)$	0.0229890	0.0808159	0.0863925	0.0413197	0.0041396
$\hat{F}_{Y_{BTR}}(t_y)$	0.0222701	0.0518875	0.0487343	0.0232861	0.0023483
$\hat{F}_{Y_{BTP}}(t_y)$	0.0854892	0.0629079	0.0066456	0.0029764	0.0004509
$\hat{F}_{Y_{SI}}(t_y)$	0.3459963	0.2536123	0.0268767	0.0119967	0.0018170
$\hat{F}_{Y_{ups}}(t_y)$	0.3501308	0.2556228	0.0271748	0.0120886	0.0018156
$\hat{F}_{Y_{st}}(t_y)$	0.0630276	0.0911751	0.0243117	0.0111936	0.0014454
$\hat{F}_{Y_{se}}(t_y)$	0.3419568	0.2516314	0.0265823	0.0119055	0.0018184
$\hat{F}_{Y_{jk}}(t_y)$	1.9741553	1.7650936	2.2395605	4.2166982	36.4674200
$\hat{F}_{Y_{gy}}(t_y)$	1.916062	1.7070734	2.2219939	4.2092540	36.4666900
$\hat{F}_{Y_{AD}}(t_y)$	0.0199238	0.0452569	0.0021598	0.0006886	0.0003170

Table 3: Percentage Relative Efficiency (PRE) for Population I-V

Estimators	Population I	Population II	Population III	Population IV	Population V
$\hat{F}_{Y_{usual}}(t_y)$	100.00	100.00	100.00	100.00	100.00
$\hat{F}_{Y_c}(t_y)$	28.85	44.64	1000.00	1499.96	3044.93
$\hat{F}_{Y_m}(t_y)$	187.50	56.82	25.64	25.42	253.77
$\hat{F}_{Y_{BTR}}(t_y)$	193.55	88.50	45.45	45.11	447.37
$\hat{F}_{Y_{BTP}}(t_y)$	50.42	72.99	333.33	352.94	2329.78
$\hat{F}_{Y_{SI}}(t_y)$	12.46	18.11	82.42	87.57	578.60
$\hat{F}_{Y_{ups}}(t_y)$	12.31	17.96	81.52	86.91	578.60
$\hat{F}_{Y_{st}}(t_y)$	68.39	50.36	91.12	93.85	726.79
$\hat{F}_{Y_{se}}(t_y)$	12.61	18.25	83.33	88.24	577.71
$\hat{F}_{Y_{jk}}(t_y)$	2.18	2.60	0.99	0.25	0.03
$\hat{F}_{Y_{gy}}(t_y)$	2.25	2.69	1.00	0.25	0.03
$\hat{F}_{Y_{AD}}(t_y)$	216.34	101.46	1025.65	1525.56	3306.58

From the numerical results presented in Tables 2 and 3 show that the proposed estimator is more efficient than the reviewed existing estimators of CDF.

Conclusion

This study proposed an efficient non-linear estimator for the estimation of a finite population CDF using simple random sampling and from theoretical and empirical comparisons, the proposed estimator was found to perform better, based on large PRE and smaller MSE. Therefore, our study suggested the use of the proposed estimator for estimating the CDF in practice than the existing estimators in the literature.

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